

Normaliz: algorithms for rational cones and affine monoids

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Osnabrück, January 15, 2013

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Definition

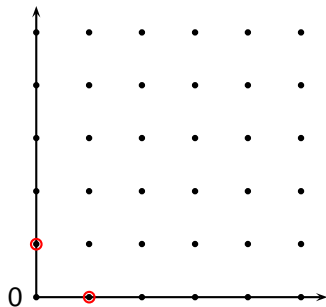
An **affine monoid** is a finitely generated submonoid of a lattice \mathbb{Z}^d , i.e.,

- $M \subset \mathbb{Z}^d$, $M + M \subset M$, $0 \in M$,
- there exist $x_1, \dots, x_n \in M$ such that

$$M = \{a_1x_1 + \dots + a_nx_n : a_i \in \mathbb{Z}_+\}.$$

M is **positive** if $x, -x \in M \Rightarrow x = 0$.

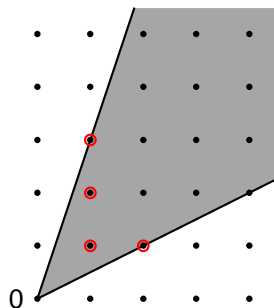
A trivial example



$$M = \mathbb{Z}_+^2$$

(unique) minimal system of generators given by $(1, 0)$, $(0, 1)$

A not so trivial example



$$M = \{x \in \mathbb{Z}^2 : x \leq 2y, 3x \geq y\}$$

(unique) minimal system of generators given by
 $(2, 1), (1, 1), (1, 2), (1, 3)$

Cones and lattices

Normaliz computes monoids that arise as intersections of cones and lattices (as the examples above):

Definition

A **(rational) cone** C is a subset

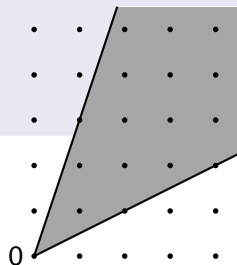
$$C = \{a_1x_1 + \cdots + a_nx_n : a_1, \dots, a_n \in \mathbb{R}_+\}$$

with a generating system $x_1, \dots, x_n \in \mathbb{Z}^d$.

C **pointed** $\iff (x, -x \in C \Rightarrow x = 0)$.

(For us) a **lattice** is a subgroup of \mathbb{Z}^d .

We will often assume $L = \mathbb{Z}^d$
 C pointed and $\dim C = d$.



Basic theorems: : the support hyperplanes

By the [theorem of Minkowski-Weyl](#) finitely generated cones can be described by finitely many inequalities:

Theorem

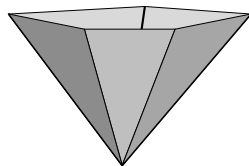
For $C \subset \mathbb{R}^d$ the following are equivalent:

- there are x_1, \dots, x_n such that $C = \{\sum a_i x_i : a_i \in \mathbb{R}_+\}$;
- there are $\lambda_1, \dots, \lambda_s \in (\mathbb{R}^d)^*$ such that $C = \{x \in \mathbb{R}^d : \lambda_i(x) \geq 0\}$.

In the case $\dim C = d$ (to which we have restricted ourselves) $\lambda_1, \dots, \lambda_s$ for minimal s define the **support hyperplanes**

$$H_i = \{x : \lambda_i(x) = 0\}$$

and the **facets** $F_i = C \cap H_i$ of C .



$x \in M$ is **irreducible** if $x = y + z \Rightarrow x = 0$ or $y = 0$.

Theorem (van der Corput)

Let M be a positive affine monoid.

- *every element of M is a sum of irreducible elements.*
- *M has only finitely many irreducible elements.*
- *The irreducible elements form the unique minimal system of generators $\text{Hilb}(M)$ of M , the **Hilbert basis**.*

In particular, monoids of type $C \cap \mathbb{Z}^d$ (C pointed, rational) have a unique minimal finite system of generators, often called $\text{Hilb}(C)$.

Basic theorems: Gordan's lemma

Theorem (Gordan)

Let $C \subset \mathbb{R}^d$ be the cone generated by $x_1, \dots, x_n \in \mathbb{Z}^d$. Then $C \cap \mathbb{Z}^d$ is an **affine monoid**.

Proof.

Let $y \in C \cap \mathbb{Z}^d$. Then there exist $a_i \in \mathbb{R}_+$ such that

$$y = a_1 x_1 + \dots + a_n x_n.$$

Write $a_i = b_i + q_i$ mit $b_i \in \mathbb{Z}_+$ and $0 \leq q_i < 1$. Then

$$y = b_1 x_1 + \dots + b_n x_n + z, \quad z = q_1 x_1 + \dots + q_n x_n \in C \cap \mathbb{Z}^d.$$

Therefore the monoid $C \cap \mathbb{Z}^d$ is generated by x_1, \dots, x_n and the finite set

$$\mathbb{Z}^d \cap \{q_1 x_1 + \dots + q_n x_n : 0 \leq q_i < 1\}$$



The tasks of Normaliz: Hilbert basis

Normaliz computes (together with other data)

$$\text{Hilb}(C \cap L)$$

Cones C and lattices L can be specified by

- **generators** $x_1, \dots, x_n \in \mathbb{Z}^d$,
- **constraints**: homogeneous systems of diophantine linear inequalities, equations and congruences,
- **relations**: binomial equations.

Normaliz has two algorithms for Hilbert bases: (1) the original Normaliz algorithm, and (2) a variant of an algorithm due to Pottier.

We concentrate on generators as input and the algorithm (1).

The tasks of Normaliz: Hilbert series

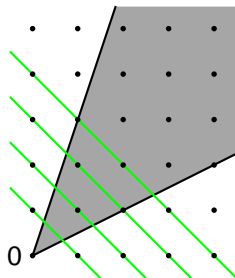
A **grading** on M is a surjective \mathbb{Z} -linear form $\deg : \text{gp}(M) \rightarrow \mathbb{Z}$ such that $\deg(x) > 0$ for $x \in M, x \neq 0$

The **Hilbert** (or Ehrhart) **function** is given by

$$H(M, k) = \#\{x \in M : \deg x = k\}$$

and the **Hilbert** (Ehrhart) **series** is

$$H_M(t) = \sum_{k=0}^{\infty} H(M, k)t^k.$$



Theorem (Hilbert-Serre, Ehrhart)

- $H_M(t)$ is a rational function
- $H(M, k)$ is a quasi-polynomial for $k \geq 0$

System of generators and reduction

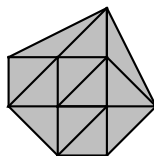
Most likely every algorithm for the computation of Hilbert bases needs two phases:

- the determination of **system of generators** E ,
- the **reduction** of E to the Hilbert basis.

We need two auxiliary, interleaved steps:

- the computation of the **support hyperplanes** of the cone,
- a **triangulation** of the cone.

A triangulation is a **decomposition** into simplicial cones: $C = \bigcup_{\sigma \in \Sigma} C_{\sigma}$.



A cone is **simplicial** if it is generated by linearly independent vectors.

Support hyperplanes: Fourier-Motzkin elimination

This is an **incremental** algorithm that builds a cone by successive extending the system of generators and determining the support hyperplanes in this process.

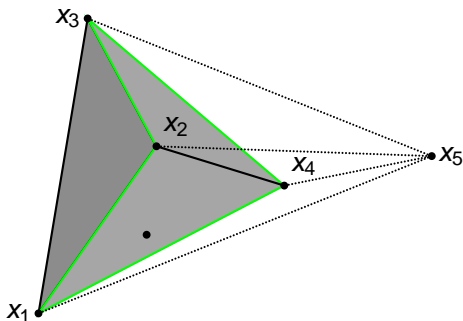
Start: We may assume that x_1, \dots, x_d are linearly independent. The computation of the **support hyperplanes** is then simply the **inversion** of the matrix with rows x_1, \dots, x_d . (In principle superfluous.)

Extension: we add x_{d+1}, \dots, x_n successively: from the support hyperplanes of $C' = \mathbb{R}_+x_1 + \dots + \mathbb{R}_+x_{n-1}$ we must compute the support hyperplanes of $C = C' + \mathbb{R}_+x_n$.

We describe this process geometrically.

We determine the boundary V of the part of C' that is visible from x_n and its decomposition into subfacets. Together with x_n these span the new facets of C' that are visible from x_n ($\lambda_i(x_n) < 0$), are discarded.

In the cross-section of a 4-dimensional cone:

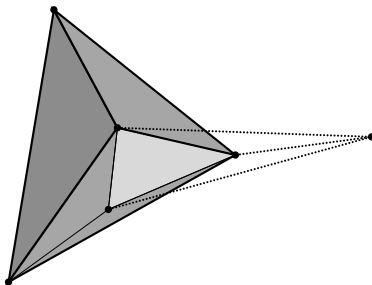


The main problem: find V .

Incremental triangulation

It follows the same inductive scheme, interleaved with Fourier-Motzkin elimination: we obtain a triangulation of C if we extend the triangulation of C' by the simplicial cones that are spanned by x_n and the facets visible from x_n .

In the cross-section of a 4-dimensional cone:



Main problem: triangulation may be very large. (Ways out: pyramid decomposition and partial triangulation.)

The reduction is in principle very simple if one knows the support hyperplanes (or rather the linear forms $\lambda_1, \dots, \lambda_s$).

Theorem

Let E be a system of generators of the positive normal affine monoid M . An element $x \in M$ is reducible if and only if there exists $y \in E$, $y \neq x$, such that $\lambda_i(x - y) \geq 0$ for $i = 1, \dots, s$.

Evidently true, since for $x, y \in \mathbb{Z}^d$ one has $x - y \in C \cap \mathbb{Z}^d$ if and only if $\lambda_i(x - y) \geq 0$ for $i = 1, \dots, s$.

Main problems:

- E is very large and many comparisons are necessary. In this case a sophisticated implementation can help to find y quickly.
- s is very large.

The steps of the algorithm

The (primal) Normaliz algorithm runs as follows:

- 1 Input of x_1, \dots, x_n , preparatory coordinate transformation.
- 2 Computation of the support hyperplanes, interleaved with the
- 3 computation of the triangulation Σ .
- 4 For every cone $C_\sigma \in \Sigma$
 - computation of a system of generators $C_\sigma \cap \mathbb{Z}^d$ (*) and
 - its reduction to the Hilbert basis HB_σ
- 5 reduction of $\bigcup_{\sigma \in \Sigma} \text{HB}_\sigma$ to $\text{Hilb}(\mathbb{C} \cap \mathbb{Z}^d)$.
- 6 inverse coordinate transformation.

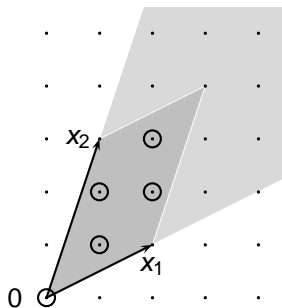
Only step (*) has not yet been explained. Or has it?

Simplicial cones

Let x_1, \dots, x_d be linearly independent and $C = \mathbb{R}_+ x_1 + \dots + \mathbb{R}_+ x_d$. In the proof of Gordan's lemma we have learnt:

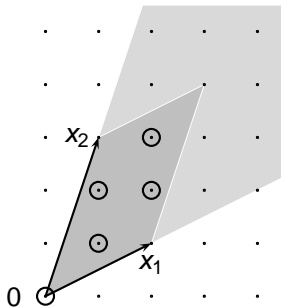
$$E = \{q_1 x_1 + \dots + q_d x_d : 0 \leq q_i < 1\} \cap \mathbb{Z}^d$$

together with x_1, \dots, x_d generate the monoid $C \cap \mathbb{Z}^d$.



Easy to see:

Every residue class in \mathbb{Z}^d/U , $U = \mathbb{Z}x_1 + \dots + \mathbb{Z}x_d$, has exactly one representative in U .



Representatives of residue classes can be quickly computed ($x_1, \dots, x_d \rightarrow$ triangular matrix) and from an arbitrary representative we obtain the one in E by [division with remainder](#).

Extensions and modifications

- Computation of **Hilbert series** (since 2000),
- based on **Stanley decompositions**: Versions 2.0–2.5 based on line shellings, now on a theorem of Köppe–Verdoolaege,
- **pyramid decomposition** “localizing” triangulation (since version 2.7),
- **partial triangulation** via “height 1 strategy” for Hilbert basis computations (since version 2.5)
- Pottiers (dual) algorithm (since version 2.1, builds C successively as an intersection of halfspaces)
- parallelization with OpenMP (since version 2.5)

Brand-new: **NmzIntegrate** computes Lebesgue integrals of polynomials over rational polytopes and generalized Ehrhart series.

Challenges mastered

	Condorcet effic. of plurality voting	linear order polytope for S_6	$5 \times 5 \times 3$ contingency tables
Reference	Schürmann	Sturmfels-Welker	Ohsugi-Hibi
computation	Ehrhart series	volume	Hilbert basis
embed dimension	24	16	55
dimension	24	16	43
# extreme rays	3928	720	75
# Hilbert basis	(25,192)	(720)	75
# supp hyperplanes	30	910	306,955
# full triangulation	347,225,775,338	5,745,903,354	(9,248,527,905)
# eval simpl cones	347,225,775,338	102,526,351	448,645
computation time	218:13:55 h	36:45 min	26:52 min

SUN xFire 4450 (parallelization 20 threads), RAM < 2 GB

Normaliz (present public version 2.8) runs on

- Apple
- Linux
- MS Windows

Access to Normaliz from

- Singular (library by WB and Christof Söger)
- Macaulay 2 (package by Gesa Kämpf)
- CoCoA (John Abbott, Anna Bigatti, Christof Söger)
- Sage (optional package by Andrey Novoseltsev)
- polymake (Andreas Paffenholz)
- Regina (for 3-manifolds by Benjamin Burton)

GUI interface [jNormaliz](#) (by V. Almendra and B. Ichim)

- Robert Koch (1997-2002, implementation in C)
- Witold Jarnicki (2003)
- Bogdan Ichim (2007–2008, completely new implementation in C++, versions 2.0, 2.1, jNormaliz)
- Christof Söger (since 2009)
- Gesa Kämpf (Macaulay 2 package)
- Andreas Paffenholz (polymake interface)
- Andrey Novoseltsev (Sage package)

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